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# Refraction simulation of nonlinear wave for Shallow Water-Like equation

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## Abstract

The generalized (3+1) dimensional Shallow Water-Like (SWL) equation, which is one of the higher dimensional evolution equations, is successfully constructed with aid of the (1/G')-expansion method,

which is one of the analytical solution instruments in mathematics. Solitary waves are depicted by assigning specific values to the parameters in the SWL equation travelling wave solutions, which have a significant place in physical energy transport. Graphics representing the solitary wave at any given moment are displayed in 2D, 3D and contours. A simulation of the wave is created for different values of the velocity of a solitary wave, which is a physical quantity. In addition, by keeping the parameters other than the rupture event of the wave constant, the situation at which the velocity the wave reaches the breakage event is discussed.

**Keywords:** Exact solution, (1/G')-expansion method, solitary wave.

### 1. Introduction

When one of the independent variables in the SWL equation depends on the time parameter t, it is defined as the nonlinear evolution equation [1]. Observations of physical phenomena and the resulting nonlinear partial differential equations (NPDEs) corresponding to these observations have always been a subject of research since. These research topics have application areas in fluid dynamics, quantum mechanics, materials science, chemistry and similar situations [2-4]. As a result of the observations in these application areas, models of situations related to physical events are created [5-7]. For this reason, firstly, the mathematical equivalents of these models were determined. In the next process, the exact solutions of these NPDEs were investigated with the help of powerful and effective methods. Generally, the solutions obtained were associated with the soliton concept first defined by Russell [8]. From this starting point, these application areas have been continuously developed and rapid progress has been made. One of the causes for this is that the travelling wave solutions found are of various types, which enabled these studies to continue continuously. When the literature is examined, it has been observed that various methods have been developed.

Some of these methods: modified sub-equation method [9], Lie transformation method [10], sine-Gordon expansion method [11], the first integral method [12], Hirota bilinear method [13] and so on [14-27].

The (3+1)-dimensional equation of generalized SWL is a nonlinear equation of evolution that has recently become very common [28].

$$u_{xxxy} + 3u_{xx}u_{y} + 3u_{x}u_{xy} - u_{yt} - u_{xz} = 0.$$
 (1.1)

Recently, there have been several articles on this equation. (G'/G)-expansion method procedure was obtained by Zayed, and travelling wave solutions were obtained with the aid of the generalized binary operator by Zhang [29-30]. With the aid of the Bernoulli sub equation process, wave solutions of Eq. (1.1) were attained by Dusunceli [31].

By using the (1/G')-expansion method, we aim to achieve travelling wave solutions for Eq. (1.1) in this study [32,33].



The (1/G') method is a method inspired by the (G'/G) method. While three different types of solutions are obtained with the (G'/G) method, the solution obtained in the (1/G') method is different from these three solutions. One of the most significant reasons for choosing this method is to shed light on the shock wave phenomenon with nonlinear wave propagation in shallow waters.

# **2.** (1/G')-Expansion Method

This method was introduced to the literature in Yokus' Phd thesis [34]. Let us consider a NPDE as follows:

$$W(u, u_{t}, u_{x}, u_{y}, u_{z}, u_{xx}, ...) = 0.$$
(2.1)

Where, let

 $u(x, y, z, t) = U(\xi) = U, \quad \xi = x + ky + mz - wt, \ w \neq 0.$ 

Here k, m are numbers of wave and w is a physical quantity and the velocity parameter of the wave. We can transform (2.1) to the following ODE for  $U(\xi)$ :

$$S(U,U',U'',...) = 0.$$
 (2.2)

Solution of Eq. (2.2) has the form

$$U(\xi) = a_0 + \sum_{i=1}^n a_i \left(\frac{1}{G'}\right)^i,$$
 (2.3)

here  $a_i$ , (i = 0, 1, 2, ..., n) are constants,  $G(\xi) = G$  provides the following quadratic linear ordinary differential equation (ODE)

$$G'' + \lambda G' + \tau = 0, \quad \tau, \lambda \in R.$$
(2.4)

The solution format produced by the method is as follows:

$$\frac{1}{G'(\xi)} = \frac{1}{-\frac{\tau}{\lambda} + A\cosh(\xi\lambda) - A\sinh(\xi\lambda)}, \quad A \in \mathbb{R}.$$
(2.5)

Considering that the solution satisfies the equation, (2.3) substituted in Eq. (2.2). To obtain the polynomial P(1/G')=0. The coefficients of all the powers of (1/G') are set to zero. Thus, a system of equations is created. By solving the system of equations, unknown constants are found.

The resulting constants are substituted in Eq. (2.3) and by applying inverse transform, a travelling wave solution of Eq. (2.1) is achieved. Applying the transform  $u = u(x, y, z, t) = U(\xi)$  in Eq. (1.1), we get

$$kU^{4} + 6kU'U'' + (kw - m)U'' = 0, \qquad (3.1)$$

where w represents the velocity of the wave. After Eq. (3.1) is integrated, the following equation is attained

$$kU''' + 3k(U')^{2} + (kw - m)U' = 0.$$
(3.2)

The *n* balancing term is a constant obtained between the highest order linear term and the highest order nonlinear term in any ODE [34]. So, balancing between highest order linear term U''' with highest nonlinear term  $(U')^2$  in Eq. (3.2), we find the balancing term n=2 and by considering in Eq. (2.3),

$$U(\xi) = a_0 + a_1 \left(\frac{1}{G'}\right) + a_2 \left(\frac{1}{G'}\right)^2.$$
 (3.3)

Let us substitute the Eq. (3.3) in the Eq. (3.2) so that the coefficients in the Eq. (3.3) can be calculated. After some mathematical operations, a polynomial equation based on (1/G') is constructed. The coefficient of each term of this polynomial is equal to zero and the

term of this polynomial is equal to zero and the following system of equations is created.

$$\frac{1}{G'[\xi]}: -m\lambda a_{1} + kw\lambda a_{1} + k\lambda^{3} a_{1} = 0,$$

$$\frac{1}{G'[\xi]^{2}}: -m\tau a_{1} + kw\tau a_{1} + 7k\lambda^{2}\tau a_{1} + 3k\lambda^{2}a_{1}^{2} - 2m\lambda a_{2} + 2kw\lambda a_{2} + 8k\lambda^{3}a_{2} = 0,$$

$$\frac{1}{G'[\xi]^{3}}: 12k\lambda\tau^{2}a_{1} + 6k\lambda\tau a_{1}^{2} - 2m\tau a_{2} + 2kw\tau a_{2} + 38k\lambda^{2}\tau a_{2} + 12k\lambda^{2}a_{1}a_{2} = 0,$$

$$\frac{1}{G'[\xi]^{4}}: 6k\tau^{3}a_{1} + 3k\tau^{2}a_{1}^{2} + 54k\lambda\tau^{2}a_{2} + 24k\lambda\tau a_{1}a_{2} + 12k\lambda^{2}a_{2}^{2} = 0,$$

$$\frac{1}{G'[\xi]^{5}}: 24k\tau^{3}a_{2} + 12k\tau^{2}a_{1}a_{2} + 24k\lambda\tau a_{2}^{2} = 0,$$

$$\frac{1}{G'[\xi]^{6}}: 12k\tau^{2}a_{2}^{2} = 0,$$
(3.4)

using a software application, obtain the  $k, \lambda, \tau, w, a_1, a_2$  and *m* constants, from Eq. (3.4).

Case 1. If

$$a_1 = -2\tau, \quad a_2 = 0, \quad m = k\left(w + \lambda^2\right),$$
 (3.5)

#### 3. Solutions of SWL Equation





**Figure1:** Graphs for the Eq. (3.6) for  $a_0 = 1, \lambda = -1, \tau = 0.1, w = 1, k = 0.1, y = 1, z = 1, A = 1.$ 

substituting values Eq. (3.5) into Eq. (3.3) and one may have an exact solution of the hyperbolic type for Eq (1.1):

$$u_{1}(x, y, z, t) = -\frac{2\tau}{-\frac{\tau}{\lambda} + A\cosh\left[\lambda\left(-tw + x + ky + kz\left(w + \lambda^{2}\right)\right)\right] - A\sinh\left[\lambda\left(-tw + x + ky + kz\left(w + \lambda^{2}\right)\right)\right]}$$
(3.6)

Case 2. If

$$a_1 = -2\tau, \quad a_2 = 0, \quad w = \frac{m - k\lambda^2}{k},$$
 (3.7)

substituting Eq. (3.7) into Eq. (3.3), one may have an exact solution of the hyperbolic type for Eq. (1.1):



**Figure 2:** Graphs for the Eq. (3.8) for  $a_0 = 1, \lambda = 0.1, \tau = 0.1, w = 1, k = 5, y = 1, z = 1, A = 1, m = 1.$ 



#### 4. Results and Discussion

We have attained the travelling wave solution to the generalized SWL equation by aid of the (1/G') method in this study. While Duran and Kaya produced travelling wave solutions in hyperbolic, trigonometric and rational forms with the sub equation method in their studies [35], in the Yokus study, travelling wave solutions were produced with the modified Kudryashov method [36]. In Yokus et al. studies, complex hyperbolic type solution was obtained with modified (1/G') method [37], and in this study, hyperbolic type



 $\{u_1, w=1.5\}$ 



**Figure3:** Graphs for the Eq. (3.6) for  $a_0 = 1, \lambda = -1, \tau = 0.1, k = 0.1, y = 1, z = 1, A = 1.$ 

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solution was produced with the (1/G') method. We especially observed that the (1/G') method is applicable for the SWL equation, which is a high dimensional evolution equation. It was observed that the solution attained by this method supports the solutions obtained in the literature. Solitary wave solutions were created with the aid of particular values given to the travelling wave solutions attained in this article. The effect of changes in the velocity parameter in the solitary solution on wave behavior was analyzed. In this analysis part, other parameters are taken as constant. It has been observed that the change in velocity causes distortions at the extremes of the wave after a certain value. By aid of Mathematica package program, this situation is presented in 3D in the simulation below.

As seen in Figure3, it has been determined that the speed factor is a very effective parameter in solitary wave solutions. As seen in the simulation presented for different values of "w" which represents the velocity of the solitary wave, it can be observed that for w = 2.5, the wave begins to exhibit behaviors different from the normal behavior at the extreme points. We also observed that the wave was broken for w = 2.7. In future studies, taking into account the changes in the coefficients of classical wave transformation, its effect on wave behavior can be examined. When Eq. (3.6) is examined carefully, the velocity parameter w affects the distribution of the travelling wave in the direction z. The wave number in the direction z of the travelling wave cannot be observed in Figure 3. Because variable z is considered as constant and z=1 is taken. In addition, the parameter  $\lambda$ , which comes from the methodology of the method and is more clearly seen in the Eq. (2.5), plays a significant role in the nonlinear distribution. It is an important parameter that affects both the wave velocity and the wave number.

The theme of discussion in this work is the physical parameter w, which represents the wave velocity. The effects of the wave velocity on the travelling wave solution and the condition that causes the wave to break are a matter of debate. Parameters other than the velocity parameter are out of the scope of this study. In the discussions about the behavior of travelling waves in the future, the k and m parameters, which affect the wave propagation in the y and z directions and represent the wave number, can be taken into account. It is also predicted that these physical discussions are valuable for experimental workers.

#### 5. Conclusion

In this manuscript, the travelling wave solutions of the generalized SWL equation were successfully obtained with the (1/G') method. It was concluded that the (1/G') method for Eq. (1), which is one of the higher



dimensional evolution equations, is applicable according to many methods we have given in the introduction. 2D, contour and 3D graphics of these solitary waves are presented. In Figure 3, the relation

between velocity parameter and u(x, y, z, t) is

presented in 3D, provided that the other parameters are taken as constant. The velocity values causing the breaking of the wave were investigated and determined. In future studies, many studies can be done on high dimensional nonlinear evolution equations with the help of this method.

#### **Author's Contributions**

**Murat Subaşı:** Assistance with the production of the manuscript, result interpretation, and analytical analysis on the structure.

Hülya Durur: Conducted literature search, drafted and authored the manuscript, performed the result analysis.

#### Ethics

Regarding the publication of this manuscript are no ethical issues.

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